

# Relating and Visualising CSP, VCR and Structural Traces

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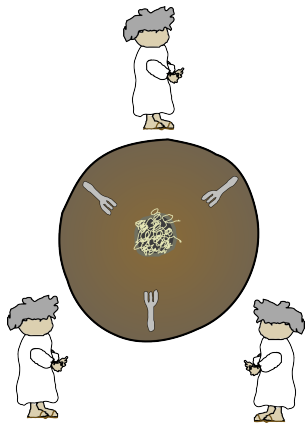
<sup>1</sup>Computing Laboratory, University of Kent, UK

<sup>2</sup>Department of Computer Science, Vassar College, NY, USA

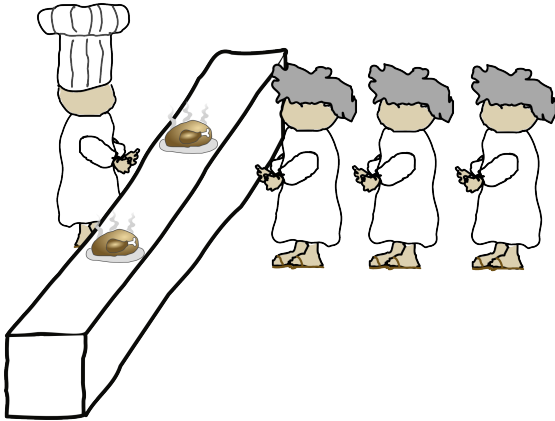
2 November 2009



# Dining Philosophers



# Starving Dining Philosophers



# Visualization: Strings and Beads

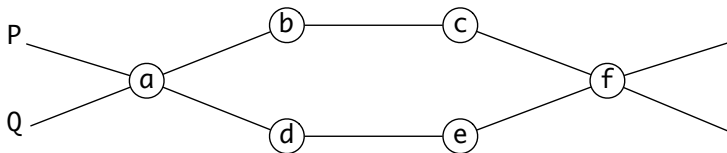
Consider the CSP system:

$$P \parallel_{\{a,f\}} Q$$

where

$$P = a \rightarrow b \rightarrow c \rightarrow f \rightarrow \text{SKIP}$$

$$Q = a \rightarrow d \rightarrow e \rightarrow f \rightarrow \text{SKIP}$$



# Visualization: Strings and Beads

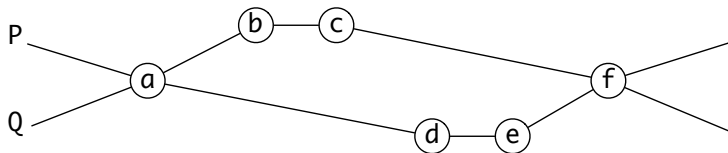
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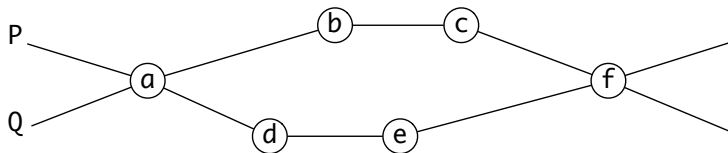
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# Visualization: Strings and Beads

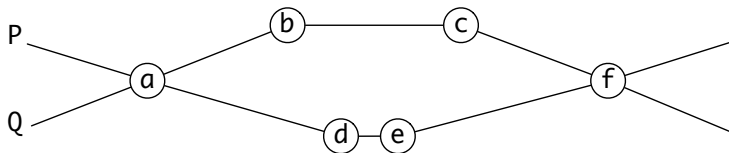
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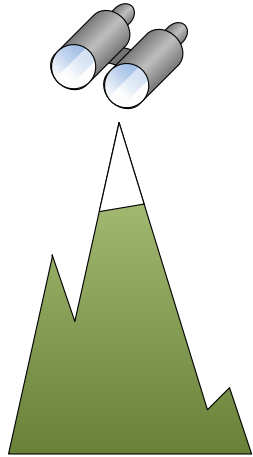
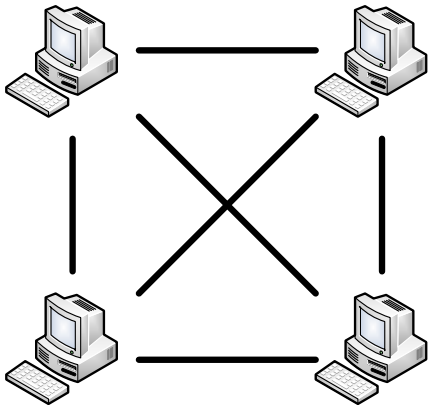
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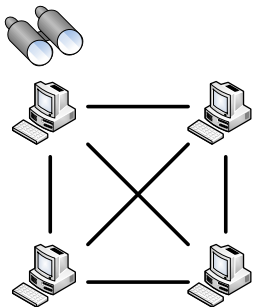


# CSP Observer

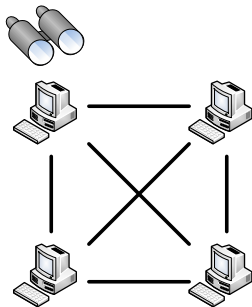
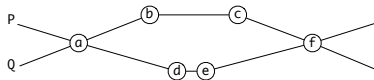
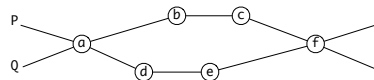
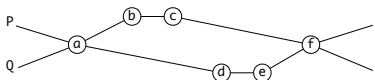
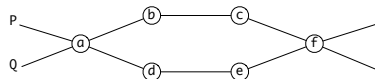




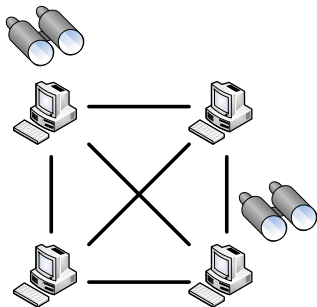
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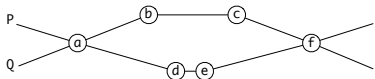
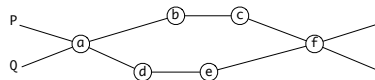
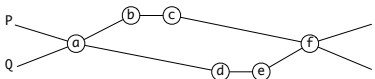
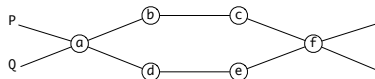
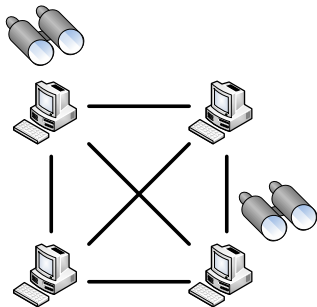
## CSP Observer


 $\langle a, b, c, d, e, f \rangle$ 
 $\langle a, d, b, c, e, f \rangle$ 
 $\langle a, b, d, c, e, f \rangle$ 
 $\langle a, d, e, b, c, f \rangle$ 
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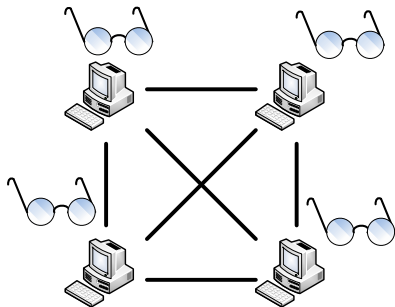
# VCR Observer(s)



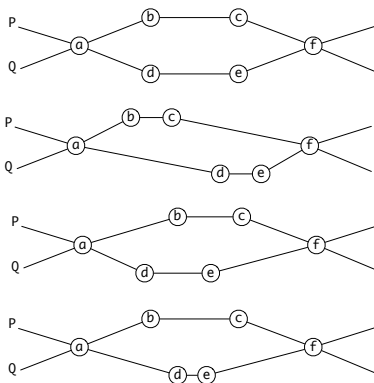
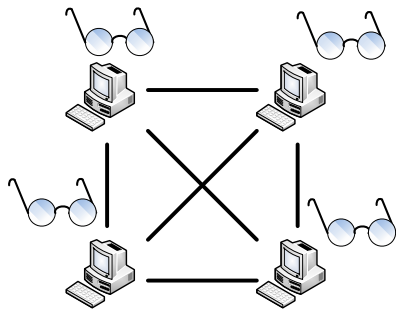
# VCR Observer(s)


 $\langle \{a\}, \{b, d\}, \{c, e\}, \{f\} \rangle$ 
 $\langle \{a\}, \{b\}, \{c, d\}, \{e\}, \{f\} \rangle$ 
 $\langle \{a\}, \{d\}, \{b, e\}, \{c\}, \{f\} \rangle$ 


# Structural Observers



# Structural Observers



$$(a \rightarrow b \rightarrow c \rightarrow f) \parallel (a \rightarrow d \rightarrow e \rightarrow f)$$



# Traces

Three types of traces:

## 1 CSP traces

- A sequence of individual events, recorded by the observer; events observed simultaneously are interleaved
- abstracts away time and space

## 2 VCR Traces

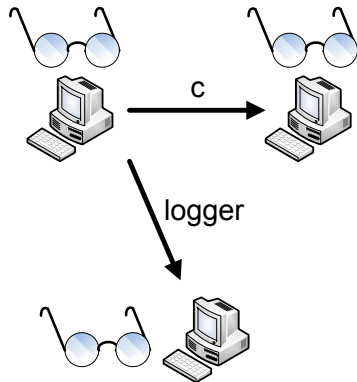
- A sequence of event multisets; multiple observers account for different views
- preserves time independence; abstracts away space

## 3 Structural Traces

- Sequential and parallel composition of the trace reflects the program's structure
- preserves time independence and space

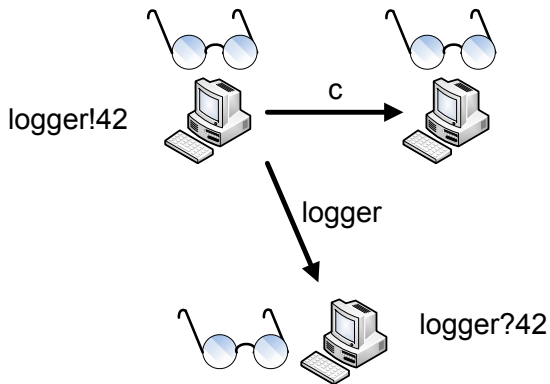


# Space and Mobility

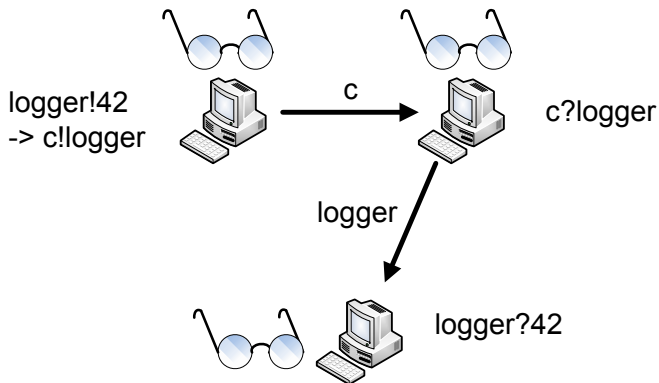




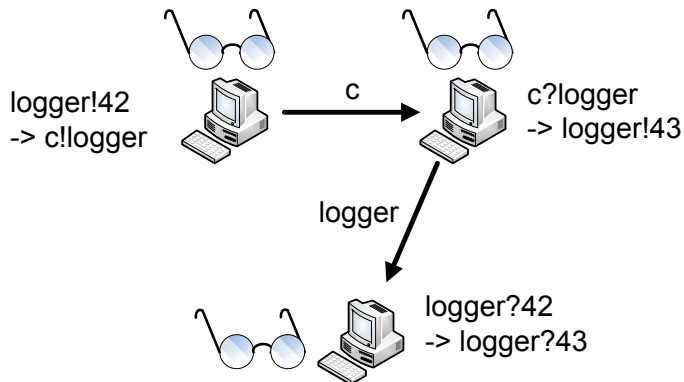
# Space and Mobility



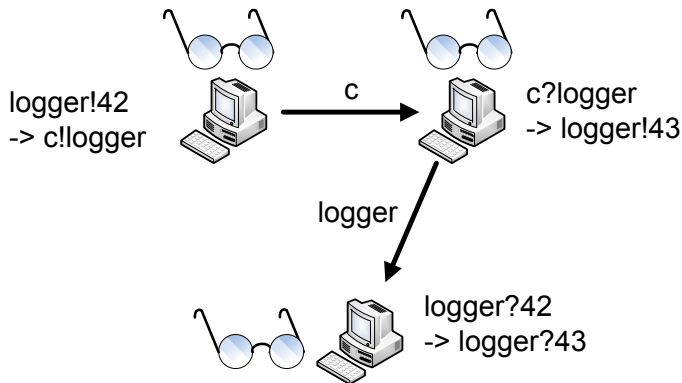
# Space and Mobility



# Space and Mobility



# Space and Mobility



$$\begin{aligned}
 & (logger!42 \rightarrow c!logger) \parallel (c?logger \rightarrow logger!43) \\
 & \parallel (logger?42 \rightarrow logger?43)
 \end{aligned}$$


# Conversion Example

CSP:

$$P = (AB \circledast AB) \parallel_{\{b\}} (b \rightarrow b \rightarrow \text{SKIP})$$

where  $AB = (a \rightarrow \text{SKIP}) \parallel (b \rightarrow \text{SKIP})$



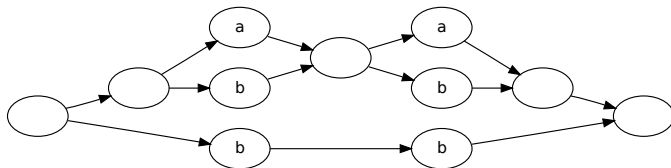
# Conversion Example

CSP:

$$P = (AB \text{ ; } AB) \parallel_{\{b\}} (b \rightarrow b \rightarrow \text{SKIP})$$

where  $AB = (a \rightarrow \text{SKIP}) \parallel (b \rightarrow \text{SKIP})$

Structural Trace Visualisation:



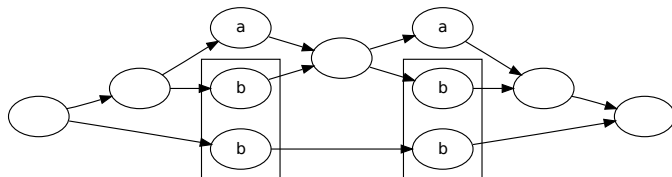
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CSP:

$$P = (AB \text{ ; } AB) \parallel_{\{b\}} (b \rightarrow b \rightarrow \text{SKIP})$$

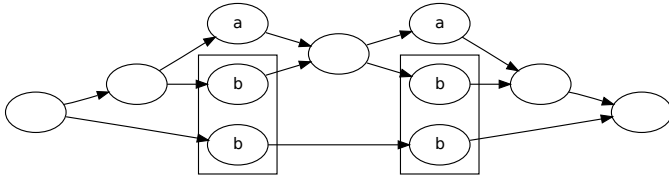
where  $AB = (a \rightarrow \text{SKIP}) \parallel (b \rightarrow \text{SKIP})$

Structural Trace Conversion Algorithm:

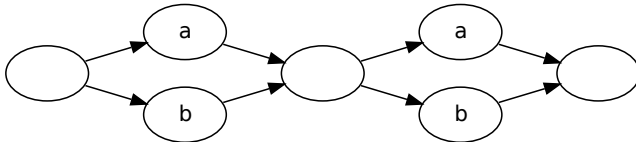


# Conversion Example

Structural Trace Conversion Algorithm:



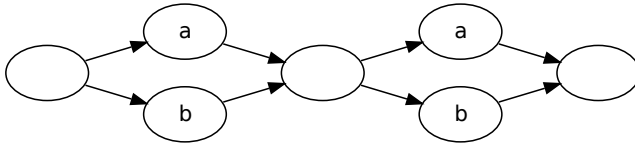
VCR Trace Visualisation:





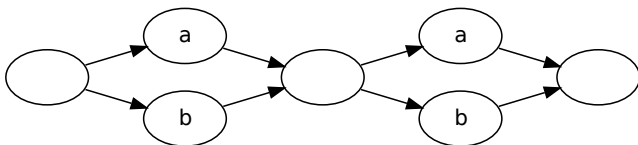
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VCR Trace Visualisation:

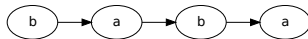
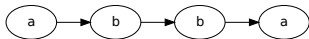
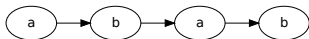


# Conversion Example

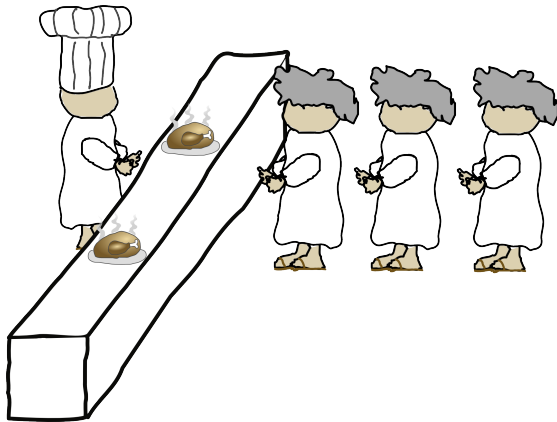
VCR Trace Visualisation:



CSP Trace Visualisation:



# Starving CHP Philosophers



# Starving CHP Philosophers Trace

```
philosopher eatChicken = forever (syncBarrier eatChicken)
```

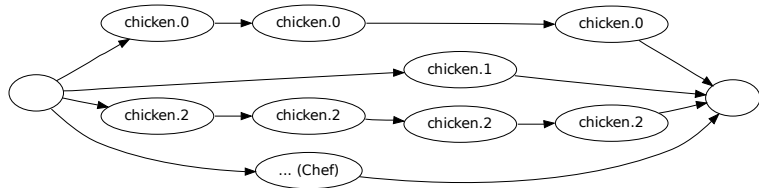
```
chef a b c = forever ((syncBarrier a <&> syncBarrier b)  
  <-> (syncBarrier b <&> syncBarrier c)  
  <-> (syncBarrier a <&> syncBarrier c))
```



# Starving CHP Philosophers Trace

philosopher eatChicken = forever (syncBarrier eatChicken)

chef a b c = forever ((syncBarrier a <&> syncBarrier b)  
 <-> (syncBarrier b <&> syncBarrier c)  
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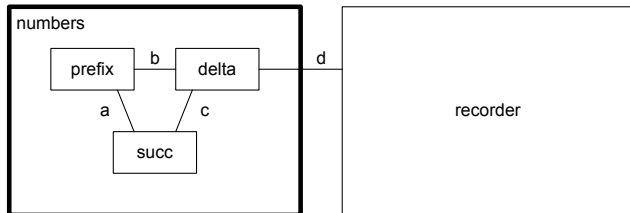


# Summary

- Traces are useful for diagnostics and observing run-time behaviour
- Structural traces
  - Most straightforward and efficient to record
  - Useful for observing mobility
- Conversion algorithms
  - One Structural trace converts to many VCR traces
  - One VCR trace converts to many CSP traces
- Visualisation
  - Graphs to represent CSP, VCR and Structural traces
  - Tool support will be beneficial

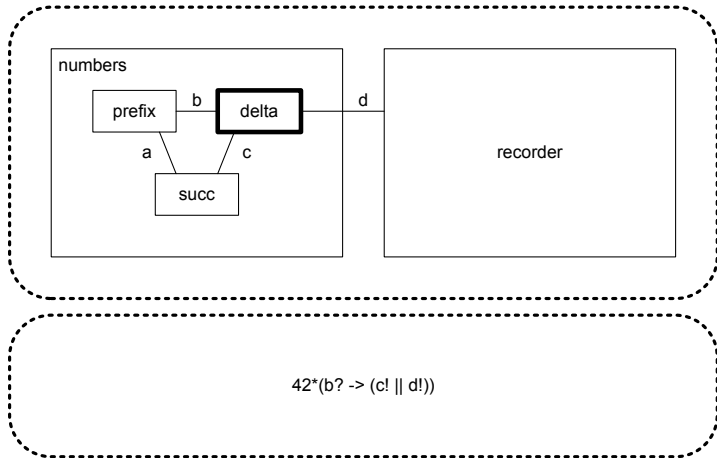


# Tools to Explore Traces



$$\begin{aligned}
 &42^*(b? \rightarrow (c! \parallel d!)) \\
 &\quad \parallel \\
 &(42^*(b! \rightarrow a?) \rightarrow b!) \\
 &\quad \parallel \\
 &42^*(c! \rightarrow a?)
 \end{aligned}$$


# Tools to Explore Traces





# Challenge: Structural traces and UTP

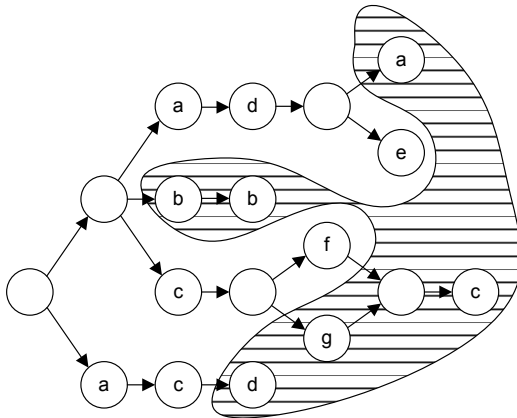


Figure: Concatenation, quotient and healthiness conditions



# Questions?

- Practical demo of traces for testing – tonight at the fringe

