

UNIVERSITY OF TWENTE.

# Design and Use of CSP Meta-Model for Embedded Control Software Development

Communicating Process Architectures 2012

Maarten Bezemer, Robert Wilterdink and Jan Broenink

Robotics and Mechatronics, University of Twente, The Netherlands



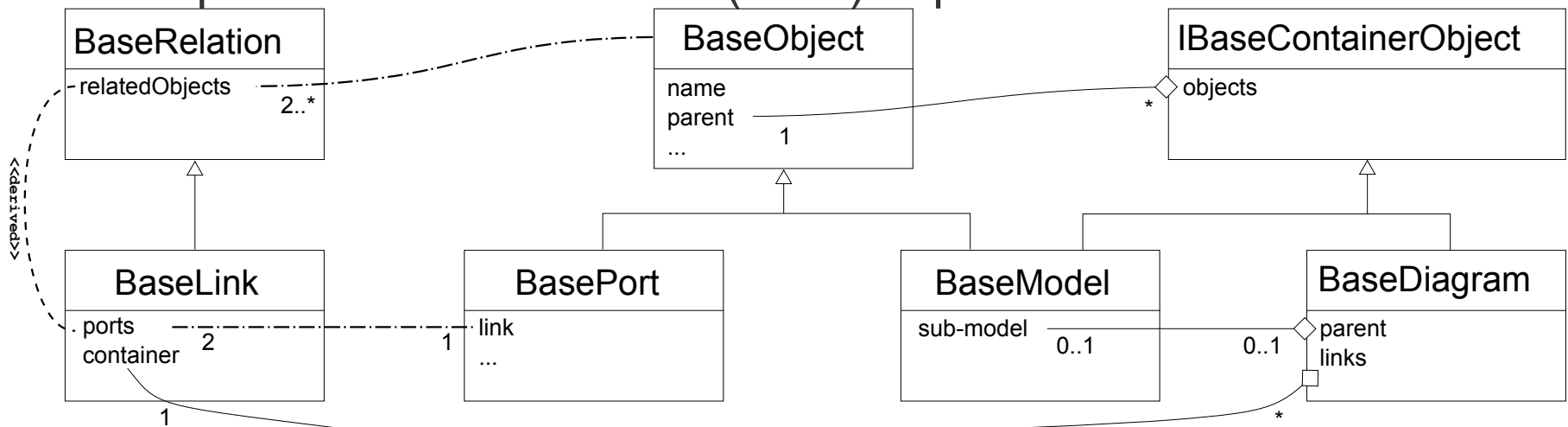
- Introduction
- CSP Meta-Model
- Use Case
- Example
- Conclusions and Future Work

Demo afterwards!

- Model-Driven Design tools help with development of complex software
- CSP helps with development of concurrent software
- The combination helps with complex concurrent software
  - Eg embedded control software for large(r) robots

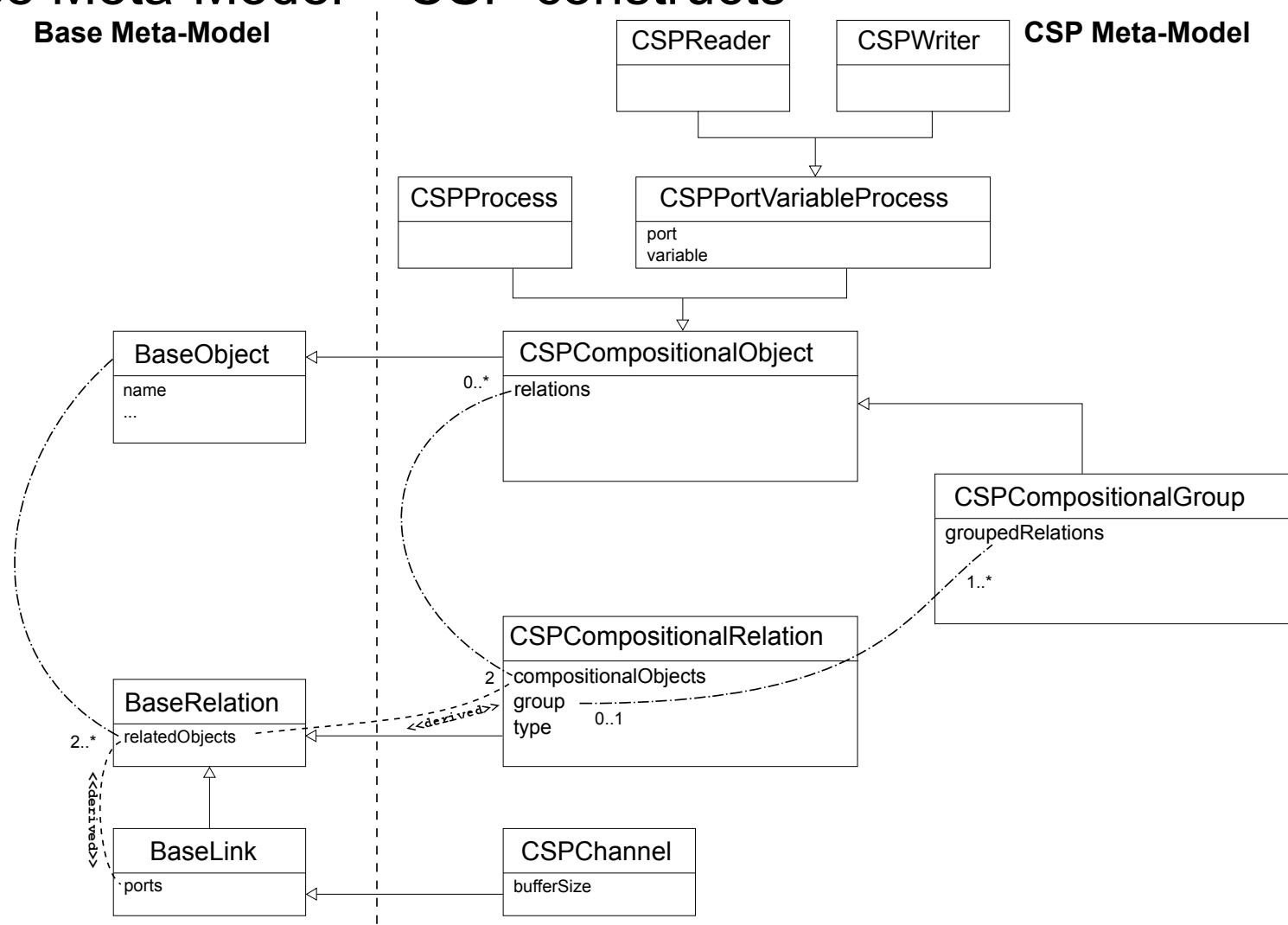
- Constituting elements of models is required
  - Multiple tools (of a tool suite) need knowledge of the models
  - Interchangeable models within a community
- A meta-model describes the format of a model
  - A meta-meta-model describes the format of a meta-model
    - etc.
- Models that conform to a meta-model use format that is known on before-hand
- No existing CSP meta-model available
  - with a focus on graphical modelling

- Modular design
- Base Meta-Model
  - Component-Port-Connector (CPC) implementation

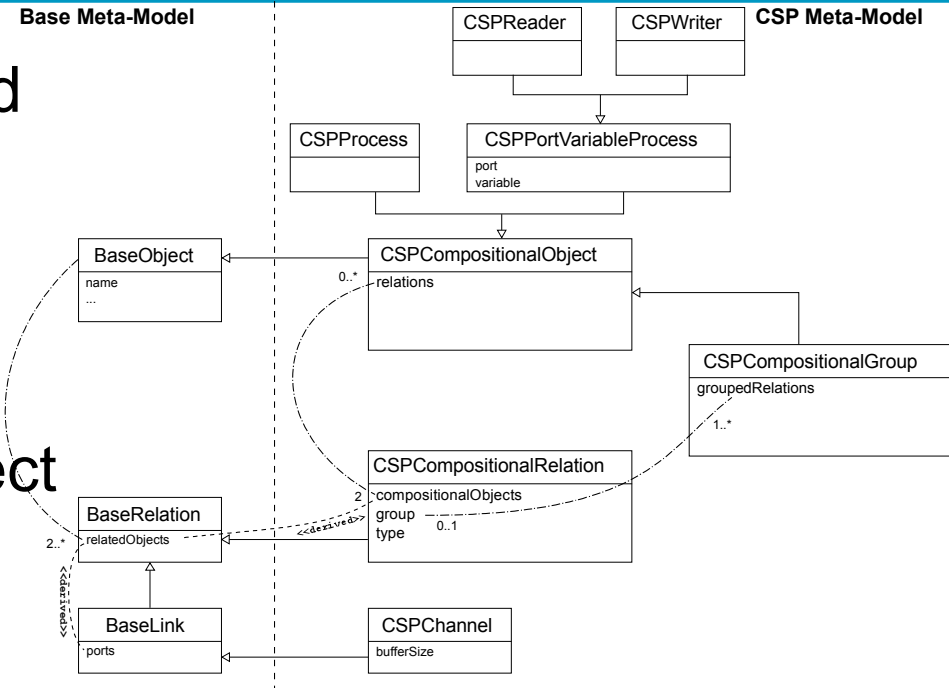


- Usable for multiple types of models
  - Graph based models
  - Communication based interfaces to external tools
  - Basically any model having 'communicating' objects

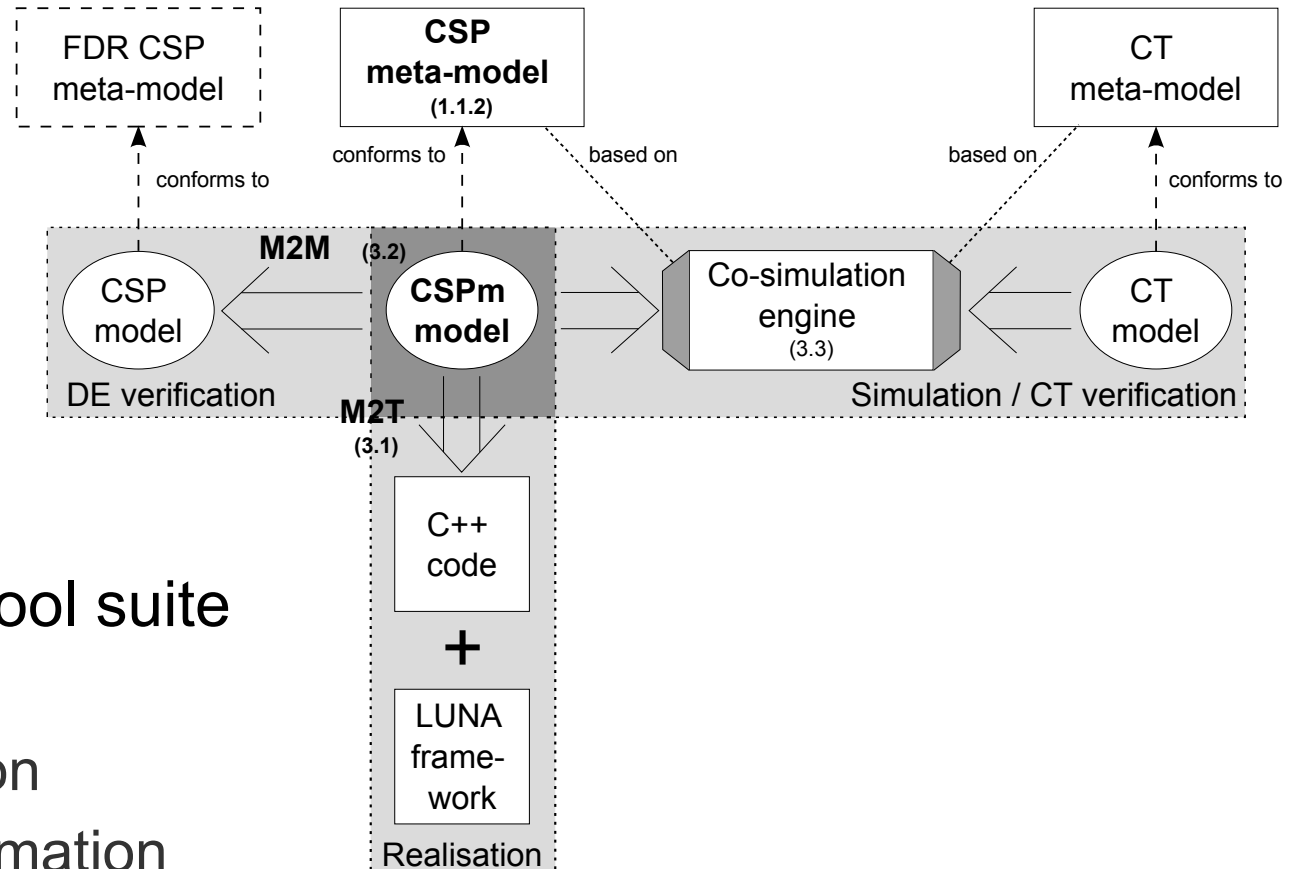
## Base Meta-Model + CSP constructs



- Strict border between Base and CSP Meta-Models
  - Convenient for tools/editors
- All CSP objects/processes are based on same CSP base object
  - Even groups
- BaseRelation defines ANY relation
  - Used to define compositional relations
- BaseLink defines a communicational relation
  - Used to define communication channels



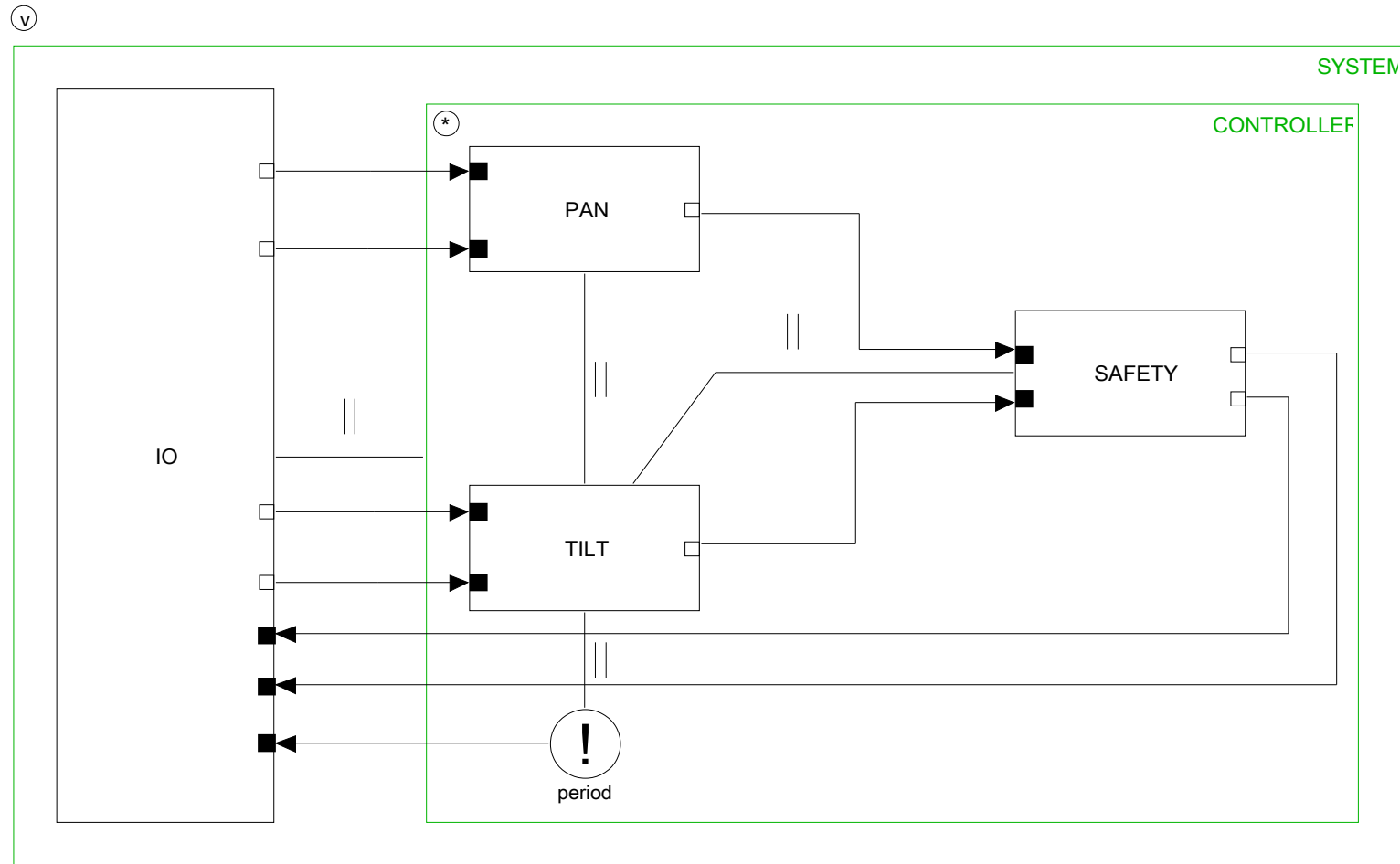
## Twente Embedded Real-time Robotic Application



## Eclipse based tool suite

- CSP Editor
- Model validation
- Model transformation
  - CSP/FDR → Formal verification of model
  - C++/LUNA → Towards on target execution of model





- Graphical representation similar to gCSP
  - More compact models, due to some changes

- Validation in editor
  - Rules are defined by Meta-Model  
'What to fill in where'
  - Addition rules for transformations
- Keeps models compliant for model transformation
  - Compatible with specific target transformation rules
    - Object names must be correct and unique (CSP and C++ LUNA)
    - Sub-models must be defined (CSP)

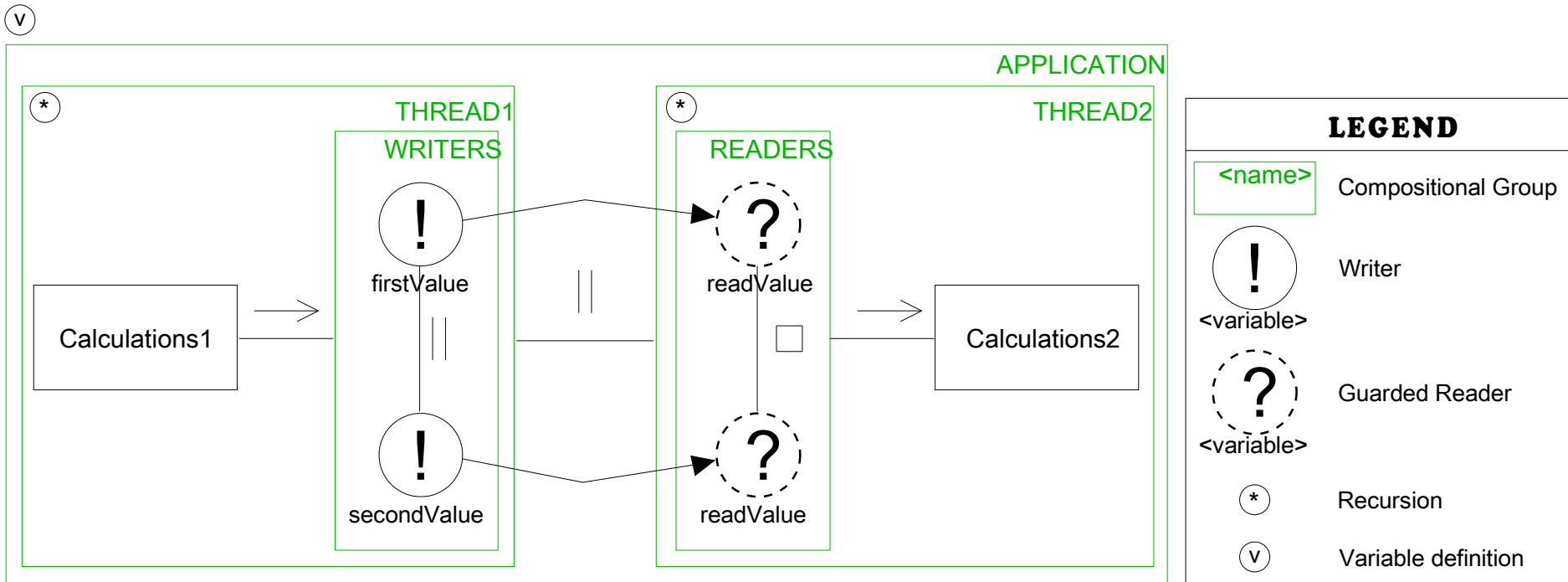
```
context CSPProcess {
  critique hasSubmodel {
    guard : CodeGenDescription.isUndefined() or CodeGenDescription == "CSP"
    check : self.submodel.isDefined()
    message : "CSP code generation will fail: " + self.name + " does not
have a sub-model set"
  }
}
```

- Possible to use external expert tools
  - FDR for formal verification of the models
- No need to reinvent these external tools!
- Put the models to actual use
  - C++/LUNA code generation to execute model on target
- Prevent errors due to manual conversion of correct models

(The demo afterwards will show actual examples)

- Representation of model in CSP (FDR)

CSPm	Meta-model representation	Additional Attributes
p = ...	CSPProcess	
	CSPCompositionalGroup	<i>groupedRelations</i> : relations that are grouped
channel c	CSPChannel	<i>ports</i> : two connected ports / processes
datatype <type> = <name>	CSPVariableDescription	<i>name</i> : name of the variable <i>type</i> : boolean, integer...
c ! <var>	CSPWriter	<i>variable</i> contains data <i>link</i> : channel to write to / read from
c ? <var>	CSPReader	
p ; q	CSPCompositionRelation	<i>type</i> = SEQ or PAR or ALT <i>compositionalObject</i> : the two related objects
p    q	CSPCompositionRelation	
p [] q	CSPCompositionRelation	
if-statement	CSPRecursionProperty	<i>expression</i> : true when another loop is required



- Corresponding CSP (FDR) code available in paper
- Real-life examples
  - JIWI and Production Cell available (JIWI will be showed in the demo afterwards)

- CSP Meta-Model usable to store CSP related models
- TERRA tool suite makes use of CSP Meta-Models
  - Editors
  - Validation
  - Transformations to plain text
- Actual suitable for Embedded Control Software Development
  - JIWI and Production Cell models are designed
  - Used by students for their assignments

- Better integration between external modelling tools and TERRA
  - 20-sim suitable for physics modelling
  - Directly integrate 20-sim models as CSP sub-models
- Building blocks
  - Provide standard Control Software functionality
  - Generic Architecture Component as a template/skeleton block
- Simulation and co-simulation capabilities
  - Better understand of models
  - Able to test a control model using a dynamics model of the plant

“Hopefully a standard meta-model will emerge that is suitable for the needs of the community and helping to improve interaction between multiple disciplines within the community.”

- Standard storage format
- Interchangeable with the tools developed within our community
- Tighter cooperation!



