



UNIVERSITY OF COPENHAGEN



Exception Handling and Checkpointing in CSP

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Outline

① Motivation



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- ① Motivation
- ② Back to Basics



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- ③ Supervisor Paradigm
 - Poison
 - Retirement



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- ④ Exception Handling
 - Fail-stop
 - Retire-like Fail-stop



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- 5 Checkpointing



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Motivation

Why Should We Care?

- Reliable software is able to handle **exceptions**.



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- Most programming languages today can handle exceptions



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Motivation

Why Should We Care?

- Reliable software is able to handle **exceptions**.
- Most programming languages today can handle exceptions internally.
- Using CSP we should be able to let **other processes** handle an exception.



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Back to Basics

What is Communication?

- A **communication** is an event done by two or more processes in parallel.



Back to Basics

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One-to-one

$$P = c!x \rightarrow P'$$

$$Q = c?x \rightarrow Q'(x)$$

$$O_2O = P \parallel Q$$



Back to Basics

What is Communication?

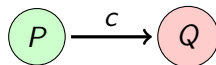
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What is Communication?

- Any-to-any channels can be “created” with the use of the interleaving operator.



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Any-to-any

$$P_i = c!x \rightarrow P'_i$$

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$$A_2A = \left(\begin{array}{c} \parallel \\ i \in 1..n \end{array} P_i \right) \parallel \left(\begin{array}{c} \parallel \\ j \in 1..m \end{array} Q_j \right)$$



Back to Basics

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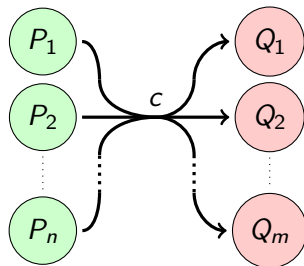
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Supervisor Paradigm

Meet the Supervisor

- A **supervisor** overlooks the channel.



Supervisor Paradigm

Meet the Supervisor

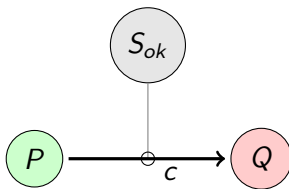
- A **supervisor** overlooks the channel.
- It controls which communication events are allowed, by engaging in them.



Supervisor Paradigm

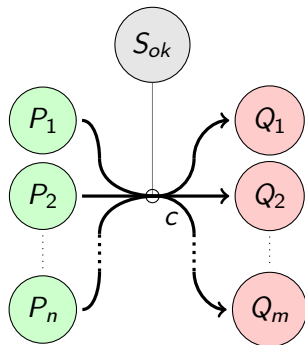
Meet the Supervisor

- A **supervisor** overlooks the channel.
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Supervisor Paradigm

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Supervisor Paradigm

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- Let us look at the supervisor process.



Supervisor Paradigm

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Supervisor

$$S_{ok} = \left(d : \{c.m \mid m \in \alpha c\} \right) \rightarrow S_{ok}$$

- Right now this allows for all communication, when run in parallel



Supervisor Paradigm

Meet the Supervisor

- Let us look at the supervisor process.

Supervisor

$$S_{ok} = \left(d : \{c.m \mid m \in \alpha c\} \right) \rightarrow S_{ok}$$

- Right now this allows for all communication, when run in parallel, however it can be modified for both **poison**, **retirement** and **exception handling**.



Poison

Killing a Network

- Each process should be able to shut down.



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- In various implementations of CSP we have a **poison** construct to shut down a network.



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- The supervisor process can be altered to encompass poison.



Poison

Killing a Network

- Each process should be able to shut down.
- In various implementations of CSP we have a **poison** construct to shut down a network.
- The supervisor process can be altered to encompass poison.
- It must have a unique event, for each other process, that should be able to poison the channel, it overlooks.



Poison

Killing a Network

Poison

$$S_{ok} = \left((d : \{c.m \mid m \in \alpha c\}) \rightarrow S_{ok} \right) \sqcap \left(\bigsqcap_{id} c_{p_{id}} \rightarrow S_e \right)$$

$$S_e = c_{poison} \rightarrow S_e \sqcap SKIP$$

$$P_i = (c!x \rightarrow P'_i) \sqcap (c_{poison} \rightarrow P_{p_i})$$

$$Q_j = (c?x \rightarrow Q'_j(x)) \sqcap (c_{poison} \rightarrow Q_{p_j})$$



Poison

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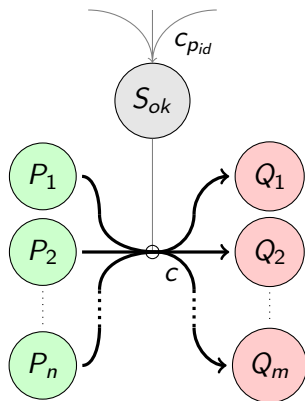
Poison

$$POISON_{A_2A} = \left(\prod_{i \in 1..n} P_i \right) \parallel \left(\prod_{j \in 1..m} Q_j \right) \parallel S_{ok}$$



Poison

Killing a Network



Retirement

Shutting Down a Network

- **Retirement** is poisons less aggressive brother.



Retirement

Shutting Down a Network

- **Retirement** is poisons less aggressive brother.
- We count reader and writers. A channel is retired if either reaches zero.



Retirement

Shutting Down a Network

Retirements Supervisor

$$S_{ok}(0, -) = S_e$$

$$S_{ok}(-, 0) = S_e$$

$$S_{ok}(n, m) = ((d : \{c.me \mid me \in \alpha c\}) \rightarrow S_{ok}(n, m))$$

$$\square_{id} (c_{rw_{id}} \rightarrow S_{ok}(n-1, m))$$

$$\square_{id} (c_{rr_{id}} \rightarrow S_{ok}(n, m-1))$$

$$S_e = c_{retire} \rightarrow S_e \square SKIP$$



Retirement

Shutting Down a Network

Retirement Network

$$RETIRE_{A_2A} = \left(\prod_{i \in 1..n} P_i \right) \parallel \left(\prod_{j \in 1..m} Q_j \right) \parallel S_{ok}(n, m)$$



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Exception Handling

How Do We Handle Exceptions?

- CSP already offers to interrupt a process via the interrupt operator.



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Interrupt

$P \Delta Q$



Exception Handling

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Interrupt

$P \Delta Q$

- This behaves as P but is interrupted on the first occurrence of an event of Q .



Exception Handling

How Do We Handle Exceptions?

- We call an outside-error a catastrophe ⚡ .



Exception Handling

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- A process that behaves as P up until a catastrophe and then behaves as Q is defined by



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Catastrophe

$$P \hat{\zeta} Q = P \Delta (\zeta \rightarrow Q)$$



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- Roscoe continues this, and creates the throw operator



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Catastrophe

$$P \hat{\zeta} Q = P \Delta (\zeta \rightarrow Q)$$

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Throw operator

$$P \Theta_{x:A} Q(x)$$



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How Do We Handle Exceptions?

- We can **catch** all errors in a process with this throw operator.



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Caught

$$P_i = (c!x \rightarrow P'_i) \Theta_{error} P_{e_i}$$

$$Q_j = (c?x \rightarrow Q'_j(x)) \Theta_{error} Q_{e_j}$$



Exception Handling

How Do We Handle Exceptions?

- We can **catch** all errors in a process with this throw operator.

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$$P_i = (c!x \rightarrow P'_i) \Theta_{error} P_{e_i}$$

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- The P_{e_i} and Q_{e_j} processes could be telling the supervisor that the process in hand is in an **exception state**.



Exception Handling

How Do We Handle Exceptions?

- We can **catch** all errors in a process with this throw operator.

Caught

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- The P_{e_i} and Q_{e_j} processes could be telling the supervisor that the process in hand is in an **exception state**.

Handled

$$P_{e_i} = c_{e_i} \rightarrow SKIP$$

$$Q_{e_j} = c_{e_j} \rightarrow SKIP$$



Fail-stop

Press the Big Red Button

- **Fail-stop** is just like poison.



Fail-stop

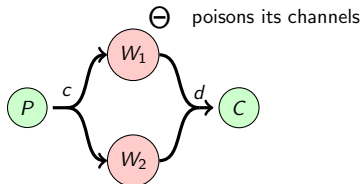
Press the Big Red Button

- **Fail-stop** is just like poison.
- It occurs when a process goes into an exception state.



Fail-stop

Press the Big Red Button



Fail-stop

Press the Big Red Button

```

1  from pycsp_import import *
2
3  @process
4  def producer(job_out):
5      for i in range(-10, 11):
6          job_out(i)
7
8  @process(fail_type = FAILSTOP)
9  def worker(job_in, job_out):
10     while True:
11         x = job_in()
12         job_out(1.0/x)
13
14  @process
15  def consumer(job_in):
16     try:
17         while True:
18             x = job_in()
19             print x
20     except ChannelFailstopException:
21         print "Caught the exception"
22
23  c = Channel()
24  d = Channel()

```

```

1  Parallel(
2     producer(-c),
3     3 * worker(+c, -d),
4     consumer(+d)
5  )

```

```

1  -0.1
2  -0.111111111111111
3  -0.125
4  -0.142857142857
5  -0.1666666666667
6  -0.2
7  -0.25
8  -0.3333333333333
9  -0.5
10 -1.0
11 1.0
12 Caught the exception

```



Retire-like Fail-stop

Press the Slightly Smaller Red Button

- Of course, **retire-like fail-stop** works like retire.



Retire-like Fail-stop

Press the Slightly Smaller Red Button

- Of course, **retire-like fail-stop** works like retire.

Retire-like network

$$P_0 = P'_0 = \text{SKIP}$$

$$P_x = c!x \rightarrow P_{x-1} \ \Theta \ P'_x$$

$$P'_x = d!x \rightarrow P'_{x-1}$$

$$F = c?x \rightarrow f!(x \cdot 2) \rightarrow F$$

$$W = d?x \rightarrow f!(x \cdot 2) \rightarrow W$$

$$C = f?x \rightarrow \text{print!}x \rightarrow C$$

$$Rnet = \left(I(P_{10}) \parallel (I(F) \parallel I(W)) \parallel I(C) \right) \\ \parallel S_{ok}(1, 1) \parallel T_{ok}(1, 1) \parallel U_{ok}(2, 1)$$



Retire-like Fail-stop

Press the Slightly Smaller Red Button

```

1  from pycsp_import import *
2
3  @process(fail_type = RETIRELIKE)
4  def producer(cout, dout, job_start,
5              job_end):
6      try:
7          for i in range(job_start, job_end):
8              cout(i)
9      except ChannelRetireLike...
10         FailstopException:
11             for i in range(i, job_end):
12                 dout(i)
13
14  @process(fail_type = RETIRELIKE)
15  def failer(cin, fout):
16      while True:
17          x = cin()
18          fout(x*2)
19          raise Exception("failed hardware")
20
21  @process(fail_type = RETIRELIKE)
22  def worker(din, fout):
23      while True:
24          x = din()
25          fout(x*2)

```

```

1  @process(fail_type = RETIRELIKE)
2  def consumer(finish):
3      while True:
4          x = finish()
5          print x
6
7  c = Channel()
8  d = Channel()
9  f = Channel()
10
11  Parallel(
12      producer(-c, -d, -10, 10),
13      failer(+c, -f),
14      worker(+d, -f),
15      consumer(+f)
16  )

```



Retire-like Fail-stop

Press the Slightly Smaller Red Button

```
1  -20
2  failed hardware
3  -18
4  -16
5  -14
6  -12
7  -10
8  -8
9  -6
10 -4
11 -2
12 0
13 2
14 4
15 6
16 8
17 10
18 12
19 14
20 16
21 18
```



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Checkpointing

We Can Roll Back Our Mistakes

- We want a way to roll back to **last valid** checkpoint.



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- A checkpoint is rendered invalid on **side-effects**, from the process



Checkpointing

We Can Roll Back Our Mistakes

- We want a way to roll back to **last valid** checkpoint.
- A checkpoint is rendered invalid on **side-effects**, from the process, that is, printing, communicating, writing to files and so on.



Checkpointing

We Can Roll Back Our Mistakes

- Let us create a process $Ch(P)$ which checkpoints P .



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- As we want to keep the latest checkpoint, we need an auxiliary process $Ch2(P, Q)$.



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- Here P is the process and Q is the latest checkpoint.



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- Let us create a process $Ch(P)$ which checkpoints P .
- As we want to keep the latest checkpoint, we need an auxiliary process $Ch2(P, Q)$.
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Checkpointing Process

$$Ch(P) = Ch2(P, P)$$



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Checkpointing Process

$$Ch(P) = Ch2(P, P)$$

- If \textcircled{c} is a **checkpoint event**, \textcircled{r} is a **roll back event**, and $P = (x : A \rightarrow P(x))$ then $Ch2(P, Q)$ can be defined as



Checkpointing

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Checkpointing Process

$$Ch(P) = Ch2(P, P)$$

- If \odot is a **checkpoint event**, \ominus is a **roll back event**, and $P = (x : A \rightarrow P(x))$ then $Ch2(P, Q)$ can be defined as

Aux. Checkpointing

$$Ch2(P, Q) = \left(x : A \rightarrow Ch2(P(x), Q) \right. \\ \left. \mid \odot \rightarrow Ch2(P, P) \right) \ominus \ominus \rightarrow Ch2(Q, Q)$$



Checkpointing

We Can Roll Back Our Mistakes

- With this we can checkpoint an **entire network** with



Checkpointing

We Can Roll Back Our Mistakes

- With this we can checkpoint an **entire network** with

Checkpoint a Network

$$Ch(P \parallel Q)$$



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- ... or **individual processes** with



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Checkpoint a Network

$$Ch(P) \parallel Ch(Q)$$



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We Can Roll Back Our Mistakes

- Having just one © will require **every process** to checkpoint at the same time.



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- Having just one © will require **every process** to checkpoint at the same time.
- A better way is to have all processes which **engages in a communication** to checkpoint at the same time.



Checkpointing

We Can Roll Back Our Mistakes

- Having just one © will require **every process** to checkpoint at the same time.
- A better way is to have all processes which **engages in a communication** to checkpoint at the same time.
- Recalling that processes on each side of the communication are interleaving, only two of them will checkpoint, the sender and the receiver.



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We Can Roll Back Our Mistakes

- This requires a small change to *Ch2*.



Checkpointing

We Can Roll Back Our Mistakes

- This requires a small change to $Ch2$.

New Aux. Checkpointing

$$Ch2(P, Q) = \left(x : A \rightarrow Ch2(P(x), Q) \right. \\ \left. \square_{c \in \alpha P} (\odot_c \rightarrow Ch2(P, P)) \right) \ominus \\ \square_{c \in \alpha P} (\mathfrak{r}_c \rightarrow Ch2(Q, Q))$$



Checkpointing

We Can Roll Back Our Mistakes

- The **supervisor** will have to be in on the checkpointing, so we change it to



Checkpointing

We Can Roll Back Our Mistakes

- The **supervisor** will have to be in on the checkpointing, so we change it to

New Aux. Checkpointing

$$S_{ok} = \left(d : \{c.me \mid me \in c\} \right) \rightarrow \textcircled{c}_c \rightarrow S_{ok}$$

$$\square \left(\textcircled{r}_c \rightarrow S_{ok} \right)$$

- To keep it simple this is missing all the poison and retire abilities.



Checkpointing

We Can Roll Back Our Mistakes

Checkpointing network

$$A = c!(" Ping") \rightarrow c?y \rightarrow a!y \rightarrow A$$

$$A' = a?x \rightarrow f!x \rightarrow A'$$

$$B = c?x \rightarrow c!(" Pong") \rightarrow b!x \rightarrow B$$

$$B' = b?x \rightarrow f!x \rightarrow B'$$

$$C_0 = f_{poison} \rightarrow SKIP$$

$$C_n = f?x \rightarrow print!x \rightarrow C_{n-1}$$

$$CPNet = \left(Ch(A) \parallel Ch(B) \right) \parallel \left(Ch(A') \parallel Ch(B') \right) \parallel Ch(C_{100}) \\ \parallel S_{ok}(2, 2) \parallel T_{ok}(1, 1) \parallel U_{ok}(1, 1) \parallel V_{ok}(2, 1)$$



Checkpointing

We Can Roll Back Our Mistakes

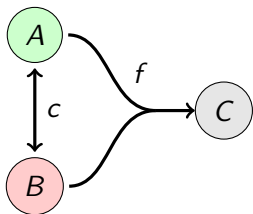


Figure: Programming model

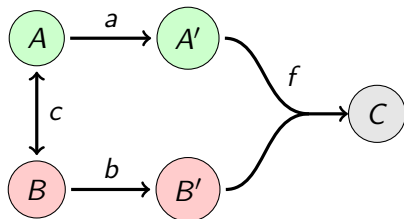


Figure: CSP model



Checkpointing

We Can Roll Back Our Mistakes

```

1  from pycsp_import import *
2  from random import randint
3
4  @process(fail_type = CHECKPOINT)
5  def A(cout, cin, fout):
6      while True:
7          cout("Ping")
8          fout(cin())
9
10 @process(fail_type = CHECKPOINT,
11          retries = -1)
12 def B(cout, cin, fout):
13     while True:
14         x = cin()
15         cout("Pong")
16         # This next line fails
17         # roughly half the time
18         1/randint(0, 1)
19         fout(x)
20
21 @process(fail_type = CHECKPOINT)
22 def C(fin, num):
23     i = load(i = 1)
24     for i in range(i, num):
25         f = fin()
26         print i, f
27     poison(fin)

```

```

1  c = Channel()
2  f = Channel()
3
4  Parallel(
5      A(-c, +c, -f),
6      B(-c, +c, -f),
7      C(+f, 100)
8  )

```

```

1  0 Ping
2  1 Pong
3  2 Ping
4  3 Pong
5  4 Ping
6  5 Pong
7  6 Ping
8  7 Pong
9  8 Ping
10 ...
11
12
13
14
15 ...
16 99 Pong

```



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Conclusions

- Presented a **supervisor paradigm**
 - This is helping **poison**, **retirement** as well as **exception handling**.



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- Shown and implemented **fail-stop** and **retire-like fail-stop**.



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- Presented a **supervisor paradigm**
 - This is helping **poison**, **retirement** as well as **exception handling**.
- Shown and implemented **fail-stop** and **retire-like fail-stop**.
- Shown and implemented **checkpointing** and **roll back**.



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Work Left to be Done

- Only works on **on**-processes, as described by Roscoe in *On the expressiveness of CSP, feb. 2011*



Work Left to be Done

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- If the process is not on the form $P = (x : A \rightarrow P(x))$ we cannot create $Ch2(P, Q)$.



Work Left to be Done

- Only works on **on**-processes, as described by Roscoe in *On the expressiveness of CSP, feb. 2011*
- If the process is not on the form $P = (x : A \rightarrow P(x))$ we cannot create $Ch2(P, Q)$.
- Let us say we have two processes P and Q

“On”-process

$$P = c \rightarrow (a \rightarrow STOP \sqcap b \rightarrow STOP)$$

$$Q = c \rightarrow a \rightarrow STOP \sqcap c \rightarrow b \rightarrow STOP$$

- These are equivalent, however, they are checkpointed in different ways after c .



Work Left to be Done

“On”-process checkpoint

$$P \Rightarrow Ch2(a \rightarrow STOP \sqcap b \rightarrow STOP, \\ a \rightarrow STOP \sqcap b \rightarrow STOP)$$

and

$$Q \Rightarrow Ch2(a \rightarrow STOP, a \rightarrow STOP) \\ \text{or } Ch2(b \rightarrow STOP, b \rightarrow STOP)$$

- Some investigation needs to be put into whether or not it is possible to create $Ch2(P, Q)$ for all processes.



Work Left to be Done

- The programmer needs to make sure that the processes do not have **side-effects**. No warnings are given.



Work Left to be Done

- The programmer needs to make sure that the processes do not have **side-effects**. No warnings are given.
- The checkpoints could be used as a starting point for other processes.
 - In a real-world application, the processes could be stopped, moved and restarted at the same point on different hardware.



Thank you very much

Questions?

